# **18<sup>th</sup> International Symposium on Visual Computing**

October 16-18, 2023, Lake Tahoe, Nevada, USA



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Registration Desk Hours: Sunday, October 15<sup>th</sup>, 2023 (4pm – 6pm) Monday, October 16<sup>th</sup> – Wednesday, October 18<sup>th</sup>, 2023 (8am-5:30pm)





# Monday, October 16<sup>th</sup>

8:50 - 9:00	Welcome – <u>George Bebis</u> , University of Nevada, Reno			
9:00–10:00		<i>Keynote: <u>Han-Wei Shen</u>, Ohio State University, USA</i> (Sand Harbor II) Chair: <u>George Bebis</u>		
		Parallel S	Sessions	
10:10-12:10	ST: Biomedical Image Analysis Techniques for Cancer Visualization (Tahoe A&B)   Detection, Diagnosis and Management (Sand Harbor II) Chair: <u>Ahmad Tafti</u>			
	10:10	Parvaneh Aliniya, Mircea Nicolescu, Monica Nicolescu and George Bebis. Hybrid Region and Pixel-Level Adaptive Loss for Mass Segmentation on Whole Mammography Images	Jiahang Huang, Andrew Ni, Jasmine Zhang, Hongyi Zhu and Hui Zhang. Visualizing Multimodal Time Series at Scale	
	10:30	Dikshant Sagar, Mohammad Pourhomayoun and Navid Amini. Deep Learning Based GABA Edited-MRS Signal Reconstruction	<b>Chenguang Xu, Sarah Brown, Christan Grant and Chris</b> <b>Weaver</b> . Hybrid Tree Visualizations for Analysis of Gerrymandering	
	10:50	Marc Berghouse, George Bebis and Alireza Tavakkoli. Investigating the Impact of Attention on Mammogram Classification	Zhiyuan Cheng, Zeyuan Li, Zhepeng Luo, Mayleen Liu, Jonathan D'Alonzo and Chaoli Wang. ArcheryVis: A Tool for Analyzing and Visualizing Archery Performance Data	
11:10-11:30		Coffee	Break	
	11:30	Bharath Srinivas Prabakaran, Erik Ostrowski and Muhammad Shafique. ReFit: A Framework for Refinement of Weakly Supervised Semantic Segmentation using Object Border Fitting for Medical Images	Tommy Dang, V.T. Ngan Nguyen, Jie Li, Alan Sill and Yong Chen. Spiro: Order-preserving Visualization in High Performance Computing Monitoring	
	11:50	Santiago Vallejo Silva et al., A Data-centric Approach for Pectoral Muscle Deep Learning Segmentation Enhancements in Mammography Images	Tim Büchner, Sven Sickert, Gerd Fabian Volk, Orlando Guntinas-Lichius and Joachim Denzler. From Faces To Volumes - Measuring Volumetric Asymmetry in 3D Facial Palsy Scans	
10:10-12:10	Video Analysis and Event Recognition (Sand Harbor I) Chair: <u>Mircea Nicolescu</u>			
	10:10	10:10 Thura Zaw, Jiaxin Zhou and Takashi Komuro. Comparison of Autoencoder Models for Unsupervised Representation Learning of Skeleton Sequences		
	10:30Ryuhei Ando, Yasunori Babazaki and Katsuhiko Takahashi. Local and Global Context Reasoning for Spatio-Temporal Action Localization			
	<b>10:50</b> Jobin Idiculla Wattasseril, Sumit Shekhar, Jürgen Döllner and Matthias Trapp. Zero-Shot Video Moment Retrieval using BLIP-based Models			
11:10-11:30		Coffee	Break	
	Fabian Sturm, Rahul Sathiyababu, Harshitha Allipilli, Elke Hergenroether and Melanie Siegel. Self- Supervised Representation Learning for Fine Grained Human Hand Action Recognition in Industrial Assembly Lines		<b>pilli, Elke Hergenroether and Melanie Siegel</b> . Self- ed Human Hand Action Recognition in Industrial Assembly	
	11:50			
12:10-1:30	Lunch Break			

1:30-2:30	<i>Keynote: <mark>David Fleet</mark>, <b>University of Toronto &amp; Google DeepMind, Canada</b> (Sand Harbor II) Chair: <u>Mircea Nicolescu</u></i>		
	Tutorials		
2:40-6:00	Tutorial 1 (Tahoe A&B)	Tutorial 2 (Sand Harbor I)	
2:40-4:10	Ethics, Bias and Responsible AI: Challenges and Mitigation Strategies Organizer: Marina L. Gavrilova, Department of Computer Science, University of Calgary	Immersive ParaView: New immersive visualization capabilities Organizers: William Sherman, National Institute of Standards and Technology (NIST) Simon Su, National Institute of Standards and Technology (NIST)	
4:10-4:30	Coffee	Break	
4:30-6:00	Ethics, Bias and Responsible AI: Challenges and Mitigation Strategies (cont'd)	Immersive ParaView: New immersive visualization capabilities (cont'd)	
2:40-7:00	Tutorial 3 (Sand Harbor II)		
2:40-4:10	Explainable Deep Few-shot Learning on the Cloud and its Application in Medical Imaging Informatics (cont'd) <u>Organizers:</u> Ahmad P. Tafti, Ph.D., University of Pittsburgh Soheyla Amirian, Ph.D., University of Georgia Arvind Rao, Ph.D., University of Michigan Iman Zadeh, Ph.D., Oracle Bryan Barker, Ph.D., Oracle Johannes Plate, MD, Ph.D., University of Pittsburgh Shandong Wu, Ph.D., University of Pittsburgh		
4:10-4:30	Coffee Break		
4:30-7:00	Explainable Deep Few-shot Learning on the Cloud and its Application in Medical Imaging Informatics (cont'd)		

9:00-10:00	Keynote: Daphna Weinshall, Hebrew University of Jerusalem, Israel (Sand Harbor II) (Cancelled due to recent developments in Israel)			
		Para	llel Sessions	
10:10- 12:10	ST	ST: Generalization in Visual Machine Learning (Sand Harbor II) Chair: Mohamed Shebata		
	10:10	Muhammad Shaheryar, Lamyanba Laishram, Jong Taek Lee and Soon Ki Jung. Latent Space Navigation for Face Privacy: A Case Study on the MNIST Dataset	Varun Ramakrishnan and Tim McGraw. Water Animation Using Coupled SPH and Wave Equation	
	10:30	Islam Osman, Islam Adel and Mohamed Shehata. Domain Generalization for Foreground Segmentation Using Federated Learning	Laura Fink, Daniel Keitel, Marc Stamminger and Joachim Keinert. UniTorch - Integrating Neural Rendering into Unity	
	10:50	Jacob Bond, Siddhartha Gupta and Thanura Elvitigala. Probabilistic Local Equivalence Certification for Robustness Evaluation (Recorded)	Guanzhou Ji, Azadeh Sawyer and Srinivasa Narasimhan. Virtual Home Staging: Inverse Rendering and Editing an Indoor Panorama under Natural Illumination	
11:10- 11:30		Coffee Break		
	11:30	Jean-Baptiste Weibel, Paolo Sebeto, Stefan Thalhammer and Markus Vincze. Challenges of Depth Estimation for Transparent Objects	Alexander Komar and Ursula Augsdörfer. SwarmCurves: Evolutionary Curve Reconstruction	
	11:50	Shahzad Ali, Yu Rim Lee, Soo Young Park, Won Young Tak and Soon Ki Jung. Volumetric Body Composition through Cross- Domain Consistency Training for Unsupervised Domain Adaptation		
10:10- 12:10	Medical Image Analysis (Sand Harbor I) Chair: <u>Wei Zeng</u>			
	10:10	10:10 Wei Zeng, Xuebin Chang, Liqun Yang, Muhammad Razib, Zhong-Lin Lv and Yi-Jun Yang. Brain Cortical Surface Registration with Anatomical Atlas Constraints		
	10:30	10:30 Ibsa Jalata and Ukash Nakarmi. When System Model meets Image Prior: An Unsupervised Deep Learning Architecture for Accelerated Magnetic Resonance Imaging		
	<b>10:50</b> Sean Wu, Naoki Kaneko, Steve Mendoza, David Liebeskind and Fabien Scalzo. 3D Reconstruction from 2D Cerebral Angiograms as a Volumetric Denoising Problem			
11:10- 11:30	Coffee Break			
	11:30	Jiadong Yu and Rahul Singh. An Integrated Sha Phenotypes in Drug Screening	ape-Texture Descriptor for Modeling Whole-Organism	
	11:50 Alan Okinaka, Gulfam Saju and Yuchou Chang. Enhancing Image Reconstruction via Phase-Constrained Data in an Iterative Process			
12:10-1:30	Lunch Break			

# Tuesday, October 17<sup>th</sup>

1:30-2:30	Keynote: <u>Kwang Moo Yi</u> , University of British Columbia, Canada (Sand Harbor II) Chair: <u>Marina Gavrilova</u>			
	Parallel Sessions			
2:40-3:40		Biometrics (Sand Harbor II) Chair: <u>Marina Gavrilova</u>		ST: Autonomous Anomaly Detection in Images (Tahoe A&B) Chair: <u>George Bebis</u>
	2:40	<b>Md Shopon and Marina L Gavrilova</b> . I Got Your Emotion: Emotion Preserving Face De- identification Using Injection-based Generative Adversarial Networks	Radov Halma	ran Fusek, Eduard Sojka, Jan Gaura and Jakub n. Driver Anomaly Detection Using Skeleton Images
	3:00	Nathan Thom, Andrew DeBolt and Emily Hand. DoppelVer: A Benchmark for Face Verification	Mohai Predic (record	nmad Baradaran and Robert Bergevin. Future Video tion from a Single Frame for Video Anomaly Detection ded)
	3:20	<b>M Faisal Nurnoby and El-Sayed M. El-Alfy</b> . Two-stage Face Detection and Anti-spoofing	Cheny Multi-c	<b>ing Wang and Alireza Tavakkoli</b> . Latent Diffusion based lass Anomaly Detection
3:40- 4:00		Cc	offee Bi	eak
2:40-3:40		ST: Artificial Intelligence in Aerial and Orbital Imagery (Sand Harbor I) Chair: <u>Ara Nefian</u>		
	2:40 Charalampos Zafeiropoulos et al. Investigating the impact of a low-rank tensor-based approach on deforestation imagery			
	<b>3:00</b> Jatin Katyal and Charalambos Poullis. Strategic Incorporation of Synthetic Data for Performance Enhancement in Deep Learning A Case Study on Object Tracking Tasks (Recorded)			
	3:20 Abigail Rolen and Sandeep Singh. Autonomous Navigation Via A Cascading CNN Framework Leveraging Synthetic Terrain Images			
3:40-4:00	Coffee Break			
4:00-5:30	Poster Session (Sand Harbor II) ST: Innovations in Computer Vision & Machine Learning   for Critical & Civil Infrastructures (Tahoe A&B) Chair: Nikolaos Doulamis			
			4:00	<b>Matthieu Pâques et al.</b> . Pretext Tasks in Bridge Defect Segmentation within a ViT-Adapter Framework
	4:20 lason Katsamenis et al. A Few-Shot Attention Recurrent Residual U-Net for Crack Segmentation		lason Katsamenis et al. A Few-Shot Attention Recurrent Residual U-Net for Crack Segmentation	
	(see page 9) 4:40 Polyzois Soumplis, Panagiotis Kokkinos and Emmanouel Varvarigos. Efficient Resource Provisioning in Critical Infrastructures based on Mu Agent Rollout enabled by Deep Q-Learning		Polyzois Soumplis, Panagiotis Kokkinos and Emmanouel Varvarigos. Efficient Resource Provisioning in Critical Infrastructures based on Multi- Agent Rollout enabled by Deep Q-Learning	
	5:00 Shaif Chowdhury, Sadia Nasrin Tisha, Monica McGarrity and Greg Hamerly. Video-Based Recognition of Aquatic Invasive Species Larvae Using Attention-LSTM Transformer			Shaif Chowdhury, Sadia Nasrin Tisha, Monica McGarrity and Greg Hamerly. Video-Based Recognition of Aquatic Invasive Species Larvae Using Attention-LSTM Transformer
6:30-9:30	Banquet Dinner (Sand Harbor III) Keynote: <u>Jiebo Luo, Rochester University, USA</u> (at 8pm) Chair: <u>George Bebis</u>			

# Wednesday, October 18<sup>h</sup>

9:00-10:00	Keynote: <u>Paul Kry</u> , McGill University, Canada (Sand Harbor II) Chair: <u>Simon Su</u>			
		Parallel Sessions		
10:10-12:10	ST: Compu	Data Gathering, Curation, and Generation for iter Vision and Robotics in Precision Agriculture (Sand Harbor II) Chair: <u>Dimitris Zermas</u>	<b>Virtual Reality</b> (Tahoe A&B) Chair: <u>Ourania Spantidi</u>	
	10:10	<b>Piyush Pandey, Norman Best and Jacob</b> <b>Washburn</b> . Synthetically labeled images for maize plant detection in UAS images	Adam Williams, Anil Ufuk Batmaz, Xiaoyan Zhou, Michel Pahud and Francisco Ortega. A Pilot Study Comparing User Interactions Between Augmented and Virtual Reality	
	10:30	Dario Guevara, Amogh Joshi, Pranav Raja, Elisabeth Forrestel, Brian Bailey and Mason Earles. An open source simulation toolbox for annotation of images and point clouds in agricultural scenarios	Brendan Kelley, Anil Ufuk Batmaz, Michael Humphrey, Cyane Tornatzky, Rosa Martey and Francisco Ortega. Emergent Individual Factors for AR Education and Training	
	10:50	Hanzhe Teng, Yipeng Wang, Xiaoao Song and Konstantinos Karydis. Multimodal Dataset for Localization, Mapping and Crop Monitoring in Citrus Tree Farms	Lazaros Rafail Kouzelis and Ourania Spantidi. Synthesizing Play-Ready VR Scenes with Natural Language Prompts through GPT API	
11:10-11:30		Coffee	Break	
	11:30	Aminul Huq, Dimitris Zermas and George Bebis. Identification of Abnormality in Maize Plants From UAV Images Using Deep Learning Approaches		
	11:50	<b>Emília Nogueira et al.</b> Deep Learning for Super Resolution of Sugarcane Crop Line Imagery from Unmanned Aerial Vehicles		
10:10-12:10	Segmentation (Sand Harbor I) Chair: <u>El-Sayed M. El-Alfy</u>			
	10:10	<b>10:10</b> Erik Ostrowski and Muhammad Shafique. ISLE: A Framework for Image Level Semantic Segmentation Ensemble		
	<b>10:30</b> Jerry Zhou, Jack Zhou, Bruce Gaynes, Jie Xu, Mengren Wu and Parisa Mirbod. Particulate Mapping Centerline Extraction (PMCE), a Novel Centerline Extraction Algorithm Based on Patterns in the Spatial Distribution of Aggregates			
	10:50Kenzo Milleville, Krishna Kumar Thirukokaranam Chandrasekar, Nico Van de Weghe and Steven Verstockt. Evaluating Segmentation Approaches on Digitized Herbarium Specimens			
11:10-11:30		Coffee	Break	
	11:30	11:30 Tobias Bolten, Regina Pohle-Fröhlich and Klaus D. Tönnies. Semantic Scene Filtering for Event Cameras in Long-Term Outdoor Monitoring Scenarios		
	11:50 Rohit Venkata Sai Dulam and Chandra Kambhamettu. SODAWideNet - Salient Object Detection with an Attention augmented Wide Encoder Decoder network without ImageNet pre-training			
12:10-1:30	Lunch Break			

1:30-2:30	<i>Keynote: Laura Trutoiu</i> , Magic Leap, USA (Sand Harbor II) Chair: <u>Emily Hand</u>			
		Parallel S	Sessions	
2:40-4:40		<b>Applications</b> (Sand Harbor II) Chair: <u>Radovan Fusek</u>	<b>Object Detection and Recognition</b> (Tahoe A&B) Chair: <u>Kostas Karydis</u>	
	2:40	Zachary Mossing, Kevin Hong, Fabien Scalzo and Eun Sang Cha. Foil-Net: Deep Learning- Based Wave Classification for Hydrofoil Surfing	<b>Rina Tagami, Hiroki Kobayashi, Shuichi Akizuki and</b> <b>Manabu Hashimoto</b> . Reliable Matching by Combining Optimal Color and Intensity Information based on Relationships between Target and Surrounding Objects	
	3:00	Roland Fischer, Janis Roßkamp, Thomas Hudcovic, Anton Schlegel and Gabriel Zachmann. Inpainting of Depth Images using Deep Neural Networks for Real-Time Applications	<b>Reece Walsh and Mohamed Shehata</b> . Regularized Meta- Training with Embedding Mixup for Improved Few-Shot Learning	
	3:20	Tim Büchner, Sven Sickert, Roland Graßme, Christoph Anders, Orlando Guntinas-Lichius and Joachim Denzler. Using 2D and 3D Face Representations to Generate Comprehensive Facial Electromyography Intensity Maps	Bijan Shahbaz Nejad, Peter Roch, Marcus Handte and Pedro José Marrón. Visual Foreign Object Detection for Wireless Charging of Electric Vehicles	
3:40-4:00	Coffee Break			
	4:00	Hanzhou Liu, Mi Lu, Binghan Li and Yucheng Wu. Real-world Image Deblurring via Unsupervised Domain Adaptation	Kemeng Zhao, Liangrui Peng, Ning Ding, Gang Yao, Pei Tang and Shengjin Wang. Deep Representation Learning for License Plate Recognition in Low Quality Video Images (recorded)	
	4:20		Peter Roch, Bijan Shahbaz Nejad, Marcus Handte and Pedro José Marrón. Optimizing PnP-Algorithms for Limited Point Correspondences Using Spatial Constraints	
2:40-4:40	<b>Deep Learning</b> (Sand Harbor I) Chair: <u>Emily Hand</u>			
	2:40	Alejandro Rico Espinosa, Declan McIntosh and Alexandra Branzan Albu. Unsupervised Deep-Learning Approach for Underwater Image Enhancement		
	3:00	Upendra Suddamalla, Meghana Basavaraj and Shenxin Xu. LaneNet++ : Uncertainty-aware Lane Detection for Autonomous Vehicle		
	3:20	Mihir Kulkarni and Kostas Alexis. Task-driven Compression for Collision Encoding based on Depth Images		
3:40-4:00		Coffee	Break	
	4:00	Jens Bayer, Stefan Becker, David Muench and Principal Components	Michael Arens. Eigenpatches - Adversarial Patches from	
	4:20	4:20 Huining Liang and Chandra Kambhamettu. Edge-guided Image Inpainting with Transformer		

# Poster Session (Sand Harbor II)

Tuesday, October 17<sup>th</sup> (4:00-5:30)

**Ickbum Kim and Sandeep Singh**. Bayesian Fusion inspired 3D reconstruction via LiDAR-Stereo Camera Pair

Daniel Beer and Andrea Salgian. Marimba Mallet Placement Tracker

**Mohammadreza Shakouri, Fatemeh Iranmanesh and Mahdi Eftekhari**. DINO-CXR: A Self Supervised Method Based on Vision Transformer for Chest X-Ray Classification

**Ethan Shafer, Jesse Wood, Sheyla Street, Enoch Crow and Calvin Lu**. Social Bias and Image Tagging: Evaluation of progress in state-of-the-art models

Alessandro Russo, Francesco Manigrasso, Fabrizio Lamberti and Lia Morra. L-TReiD: Logic Tensor Transformer for Re-Identification

**Stewart Muchuchuti and Serestina Viriri**. Retinal Disease Diagnosis with a Hybrid ResNet50-LSTM Deep Learning Model

**Ethan Welborn and Sotirios Diamantas**. Pothole Segmentation and Area Estimation with Deep Neural Networks and Unmanned Aerial Vehicles

**Takahiro Suzuki and Manabu Hashimoto**. Generation method of robot assembly motion considering physicality gap between humans and robots

**Ala'A Alshubbak and Daniel Görges**. A Self-Supervised Pose Estimation Approach for Construction Machines

**Tomio Goto and Akira Kuchida**. Image Quality Improvement of Surveillance Camera Images by Learning Noise Removal Method Using Noise2Noise

Alan Okinaka, Gulfam Saju and Yuchou Chang. Automating Kernel Size Selection in MRI Reconstruction via a Transparent and Interpretable Search Approach

Parminder Kaur, Daniela Gigante, Marco Caccianiga, Simonetta Bagella, Claudia Angiolini, Manolo Garabini, Franco Angelini and Paolo Remagnino. Segmentation and Identification of Mediterranean Plant Species

**Gulfam Saju, Alan Okinaka and Yuchou Chang.** Exploiting Generative Adversarial Networks in Joint Sensitivity Encoding for Enhanced MRI Reconstruction

Shamima Yasmin, Aina Chowdhury and Chowdhury Qaizar. Multisensory Modeling of Tabular Data for Enhanced Perception and Immersive User Experience

Lu-Hua Ma, En-Chen Chen and Tsai-Yen Li. Coping with Bullying Incidents by the Narrative and Multi-modal Interaction in Virtual Reality

Monday, October 16, 2023 at 9am

### Machine Learning for Scientific Data Analysis and Visualization Han-Wei Shan The Ohio State University USA

**Abstract:** In this talk, I will discuss our recent developments on using machine learning for scientific data analysis and visualization, with special focuses on visualization surrogates and compact representations for scientific data. I will first discuss how to construct visualization surrogates that can help streamline the visualization and analysis of large-scale ensemble simulations and facilitate the exploration of their immense input parameter space. Three different approaches for constructing such visualization surrogates: image space, object space, and hybrid image-object space approaches will be discussed. Then I will discuss how neural networks can be used to extract succinct representations from scientific data, and how regions of interest can be used as important measures for more efficient latent generation will be discussed.



**Speaker Bio-Sketch:** Han-Wei Shen is a Full Professor at The Ohio State University, and currently serves as the Editor-in-Chief of IEEE Transactions on Visualization and Computer Graphics. He is a member of IEEE VGTC Visualization Academy, and was the chair of the steering committee for IEEE SciVis conference from 2018-2020. His primary research interests are visualization, artificial intelligence, high performance computing, and computer graphics. Professor Shen is a winner of National Science Foundation's CAREER award and US Department of Energy's Early Career Principal Investigator Award. He received his BS degree from Department of Computer Science and Information Engineering at National Taiwan University in 1988, the MS degree in computer science from the State University of New York at Stony Brook in 1992, and the PhD degree in computer science from the University of Utah in 1998. From 1996 to 1999, he was a research scientist at NASA Ames Research Center in Mountain View California.

Monday, October 16, 2023 at 1:30pm

### Estimating the Structure and Motion of Biomolecules at Atomic Resolutions

David Fleet University of Toronto & Google DeepMind Canada

**Abstract**: One of the foremost problems in structural biology concerns the inference of the atomic-resolution 3D structure of biomolecules from electron cryo-microscopy (cryo-EM). The problem, in a nutshell, is a form of multi-view 3D reconstruction, inferring the 3D electron density of a particle from large sets of images from an electron microscope. I'll outline the nature of the problem and several of the key algorithmic developments, with particular emphasis on the challenging case in which the imaged molecule exhibits a wide range of conformational variation (or non-rigidity). Through single particle cryo-EM, methods from computer vision and machine learning are reshaping structural biology and drug discovery. This is joint work with Ali Punjani.



**Speaker Bio-Sketch:** David Fleet is a Research Scientist at Google DeepMind (since 2020) and a Professor of Computer Science at the University of Toronto (since 2004). From 2012-2017 he served as Chair of the Department of Computer and Mathematical Sciences, University of Toronto Scarborough. Before joining the University of Toronto, he worked at Xerox PARC (1999-2004) and Queen's University (1991-1998). He received the PhD in Computer Science from the University of Toronto in 1991. He as awarded an Alfred P. Sloan Research Fellowship in 1996 for his research on visual neuroscience. He received research paper awards at ICCV 1999, CVPR 2001, UIST 2003, BMVC 2009, and NeurIPS 2022. In 2010, with Michael Black and Hedvig Sidenbladh he received the Koenderink Prize for fundamental contributions to computer vision that withstood the test of time. In

2022, with Ali Punjani, he received the Paper of the Year Award from the Journal of Structural Biology for work on cryo-EM. He served as Associate Editor of IEEE Trans PAMI (2000-2004), as Program Co-Chair for CVPR (2003) and ECCV (2014), and as Associate Editor-In-Chief for IEEE Trans PAMI (2005-2008). He was Senior Fellow of the Canadian Institute of Advanced Research (2005-2019), and currently holds a Canadian CIFAR AI Chair. His current research interests span computer vision, image processing machine learning and computational biology.

### Tuesday, October 17, 2023 at 9am (Cancelled due to recent developments in Israel)

### Curriculum Learning and Active Learning, for Visual Object Recognition when Data is Scarce

Daphna Weinshall Hebrew University of Jerusalem Israel

**Abstract**: Deep learning protocols typically involve the random sampling of training examples by way of SGD. We investigated alternative paradigms, based on the empirical observation that the value of data points changes with time and network proficiency. In this talk I will start with curriculum learning, where by strategically arranging the learning data to present simpler concepts before more complex ones, networks can accelerate their understanding of the easier concepts, resulting in faster convergence and enhanced overall performance. I will then discuss active learning, where one deals with the annotation of data within a predetermined annotation budget. The objective is to select the data instances for annotation that will yield

the greatest improvement for the learner. Surprisingly, our findings challenge traditional active learning strategies, which typically assume a high budget. We demonstrate that when the budget is low, it is more beneficial to prioritize annotating a small number of examples that represent the easiest and most typical instances within the data. This stands in contrast to the conventional approach, which suggests selecting examples from the hardest and most atypical portion of the data distribution.



**Speaker Bio-Sketch:** Daphna Weinshall is a professor of Computer Science at the Hebrew University of Jerusalem, Israel. She acted as a visiting professor at MIT and NYU, and a visiting researcher at IBM Research NY, NECI Research Lab NJ, and Philips Research NY. Dr Weinshall served as an area chair on the program committees of NeurIPS, CVPR, ICCV, ECCV and IJCAI, and on the editorial boards of IEEE PAMI, CVIU and MVA. Additionally, she served as a panel chair or panel member on a number of prestigious grant evaluation committees, including the advance ERC Grants evaluation panel in computer science. Her undergraduate degree in mathematics and computer science is from Tel Aviv University, and she received her M.S. and Ph.D. in statistics (population genetics) from Tel Aviv University. Her recent work is focused on developing and expanding methodologies for deep learning in dynamical settings,

including pioneering work on curriculum learning and active learning.

Tuesday, October 17, 2023 at 1:30pm

### Have we solved image correspondences?

Kwang Moo Yi University of British Columbia Canada

**Abstract:** Finding correspondence across images is a fundamental task in computer vision, which recently, as in many areas of computer vision, have been revolutionized by deep learning. In this talk, I will talk about the state of research in finding correspondence across images, and whether this long-standing problem is actually solved. I will follow the historical trend in how the correspondence problem was tackled in our community, focusing on its application to camera pose estimation with sparse correspondences. Specifically, I will discuss how point cloud networks and deep networks with specific architectural considerations have played a key role in initial breakthroughs, and how they have now become "transformer-ized". I will finally talk about the potential of using large-scale pre-trained models for the correspondence problem, and end with some thoughts on the future of correspondence research.



**Speaker Bio-Sketch:** Kwang Moo Yi is an assistant professor in the Department of Computer Science at the University of British Columbia (UBC), and a member of the Computer Vision Lab, CAIDA, and ICICS at UBC. Before, he was at the University of Victoria as an assistant professor. Prior to being a professor, he worked as a post-doctoral researcher at the Computer Vision Lab in École Polytechnique Fédérale de Lausanne (EPFL, Switzerland), working with Prof. Pascal Fua and Prof. Vincent Lepetit. He received his Ph.D. from Seoul National University under the supervision of Prof. Jin Young Choi. He also received his B.Sc. from the same University. He serves as area chair for top Computer Vision conferences (CVPR, ICCV, and ECCV), as well as Machine Learning (NeurIPS and AAAI). He is part of the organizing committee for CVPR 2023.

### Tuesday, October 17, 2023 at 8pm

### Visual Content Manipulation by Learning Generative Models

Jiebo Luo University of Rochester USA

**Abstract**: Visual content manipulation involves modifying or re-synthesizing an input image such that the output follows a guidance input, such as a target layout, semantic clues, or new attributes. However, even with the development of deep generative models, visual content manipulation is challenging because it typically requires transferring visual patterns in a non-rigid fashion. Moreover, unsupervised learning schemes are often required to learn models without image-guidance data pairs. I will focus on how to: 1) design model architectures and mechanisms for visual pattern transfer, 2) design unsupervised learning schemes for learning from unpaired data, and 3) improve the fidelity of the generated content. Specifically, I will present research results on a range of manipulation tasks including pose-guided transfer, example-guided image synthesis, semantic local editing, image completion, and structure-guided inpainting.



**Speaker Bio-Sketch:** Jiebo Luo is the Albert Arendt Hopeman Professor of Engineering and Professor of Computer Science at the University of Rochester. His research focuses on computer vision, NLP, machine learning, data mining, social media, computational social science, and digital health. He has authored nearly 600 papers and over 90 U.S. patents. Prof. Luo is also an active member of the research community: a Fellow of NAI, ACM, AAAI, IEEE, IAPR, and SPIE, Editor-in-Chief of the IEEE Transactions on Multimedia (2020-2022), as well as a member of the editorial boards of the IEEE Transactions on Pattern Analysis and Machine Intelligence (2006-2011), IEEE Transactions on Multimedia (2004-2009, 2013-2016), IEEE Transactions on Circuits and Systems for Video Technology (2010-2012), IEEE Transactions on Big Data (2018-), Pattern Recognition (2002-2020), ACM Transactions on Intelligent Systems and Technology (2015-present), and so on. In addition, he served as an organizing or program committee member for numerous technical conferences sponsored by IEEE, ACM, AAAI, ACL, IAPR, and SPIE,

including most notably program co-chair of the 2010 ACM Multimedia Conference, 2012 IEEE Conference on Computer Vision and Pattern Recognition (CVPR), 2016 ACM Conference on Multimedia Retrieval (ICMR), and 2017 IEEE International Conference on Image Processing (ICIP).

Wednesday, October 18, 2023 at 9am

### Lights, Camera, Animation! Adaptive Simulation Methods for Training and Entertainment

Paul Kry McGill University Canada

**Abstract:** Physics-based simulations are a critical part of computer animation. This talk will provide a brief overview of new adaptive reduced methods that use rigid motion to speed up interactive and offline simulations of real-world phenomena. This includes merging rigid bodies at contacts, and rigidifying elastic bodies and shells when they are not deforming. The main challenge how to inexpensively identify when and where parts of a reduced system need more degrees of freedom. Applications and future directions will be discussed.



**Speaker Bio-Sketch:** Paul G. Kry received his B.Math. in computer science with electrical engineering electives in 1997 from the University of Waterloo, and his M.Sc. and Ph.D. in computer science from the University of British Columbia in 2000 and 2005. He spent time as a visitor at Rutgers during most of his Ph.D., and did postdoctoral work at INRIA Rhône Alpes and the LNRS at Université René Descartes. He is currently an associate professor at McGill University. His research interests are in physically based animation, including deformation, contact, motion editing, and simulated control of locomotion, grasping, and balance. He co-chaired ACM/EG Symposium on Computer Animation in 2012, Graphics Interface in 2014, and served on numerous program committees, including ACM SIGGRAPH, ACM/EG Symposium on Computer Animation, Pacific Graphics, and Graphics Interface. He is currently an associate editor for Computer Graphics Forum, and for Computers and Graphics. He heads the Computer Animation and Interaction Capture Laboratory at McGill University. Paul Kry is currently the president of the Canadian Human

Computer Communications Society, the organization which sponsors the annual Graphics Interface conference. Starting September 2016 Paul Kry served a 3-year term as a director at large on the ACM SIGGRAPH executive committee.

Wednesday, October 18, 2023 at 1:30pm

### Beyond the Specs: A Computational and Human-Centered Approach to Wearability in AR/VR

Laura Trutoiu Meta Reality Labs USA

**Abstract:** In the rapidly evolving landscape of AR/VR, 'wearability' emerges as a potentially critical aspect that can shape the future of this technology and ensure broad adoption. This talk introduces a framework for 'wearability' in AR/VR. We will go outside of the usual technical specifications like field of view or latency to consider elements of user experience, comfort, and aesthetics, all tied to human factors considerations. Furthermore, the talk will touch on how bringing a computational data-driven approach to human factors like simulation and modeling can speed up development and insights. Drawing from my industry experiences, I'll advocate for bringing more multidisciplinary expertise and collaboration to the development of next-generation wearable, AR/VR technology. Finally, I'd like the audience to consider what would it take to make AR/VR fully inclusive and wearable for everyone?



**Speaker Bio-Sketch:** Laura Trutoiu currently leads a multidisciplinary team at Meta's Reality Labs, using her background in computer graphics and robotics to tackle complex system issues. Her work focuses on bringing a computational lens to human factors and design of AR/VR headsets. Her team integrates data science, user research, hardware design, and modeling to optimize the form factor of wearables, and bridge the digital and physical worlds. Previously, Laura was a Senior Computer Scientist at Magic Leap's Advanced Technology office in Seattle, where she prototyped next generation wearable spatial computers. She earned her PhD from the Robotics Institute at Carnegie Mellon University, and her research spanned several industry labs including Disney Research, Industrial Light and Magic, and Max Planck Institute for Biological Cybernetics. In the early days of Oculus Research, she developed the first proof of concept for face-to-face communication in head-mounted displays with realistic facial animations for avatars.

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# **Special Tracks**

# **Biomedical Image Analysis Techniques for Cancer Detection, Diagnosis and Management**

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## **Generalization in Visual Machine Learning**

### **Organizers:**

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### **Autonomous Anomaly Detection in Images**

### **Organizers:**

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# Data Gathering, Curation, and Generation for Computer Vision and Robotics in Precision Agriculture

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# Artificial Intelligence in Aerial and Orbital Imagery

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# Innovations in Computer Vision & Machine Learning for Critical & Civil Infrastructures

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# Ethics, Bias and Responsible AI: Challenges and Mitigation Strategies

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# Immersive ParaView: New immersive visualization capabilities

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William Sherman, National Institute of Standards and Technology (NIST), USA Simon Su, National Institute of Standards and Technology (NIST), USA